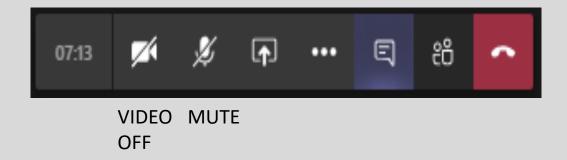
WELCOME TO TODAYS WEBINAR FROM



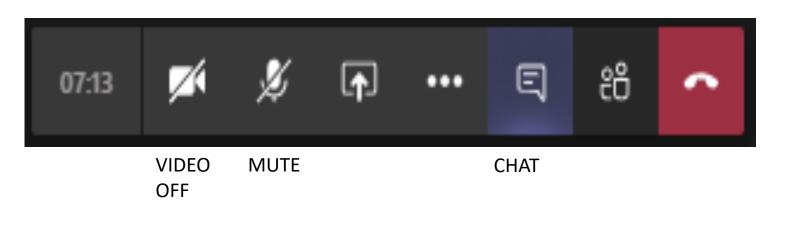
WORLD CLASS DIGITAL X-RAY SYSTEMS

The presentation will soon begin. Please prepare by disabling your camera and microphone:



THE PRACTICAL STUFF:

- VIDEO OFF
- MICROPHONE OFF
- QUESTIONS USE CHAT







AGENDA

- What differs in Aceso and Aceso+ and what do they have in common?
- Overview of system components and how they communicate
- How to navigate our documentation and schematics
- Q&A





WHO AM I?

ERIK SÄLL ARCOMA ACADEMY MANAGER

- 15 years of experience with medical x-ray equipment
- Hands on technical background (service/installation/troubleshooting)
- Focusing majority of time on training and knowledge transferring activities





WHAT DIFFERS BETWEEN ACESO+ AND ACESO?









Aceso+

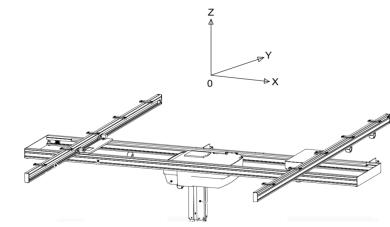
Arcoma product name = Precision

Most advanced positioning system provided by Arcoma:

- Fully automated system
 with motorized movements in X, Y, Z, and A, B directions
- Configurable autopositions with various mode functionalities
- Stitching available towards Wallstand and Table

External service software for calibration









Aceso

Arcoma product name = Intuition

Basic positioning system provided by Arcoma:

- Motorized movements in Z directions only
- Autotracking functionality
- Stitching available towards Wallstand
- Two table types available
- Integrated service software for calibration









CMP200 Generator



CXDI Control Software NE |

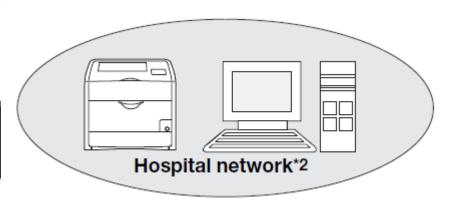


Overwrap software



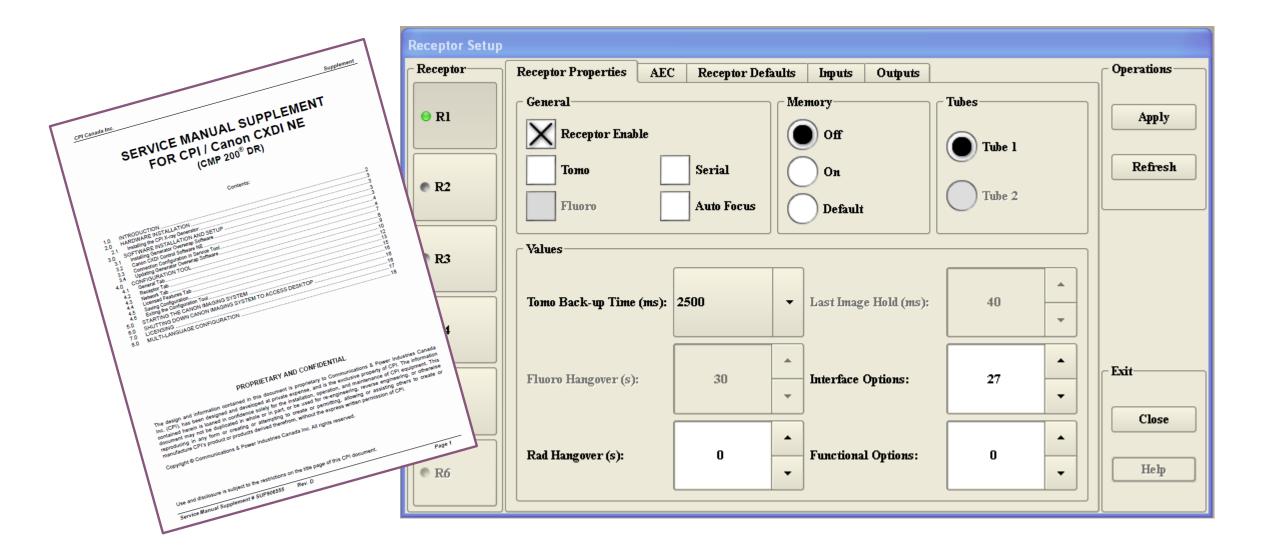
Positioning system with tube screen (Intuition or Precision)



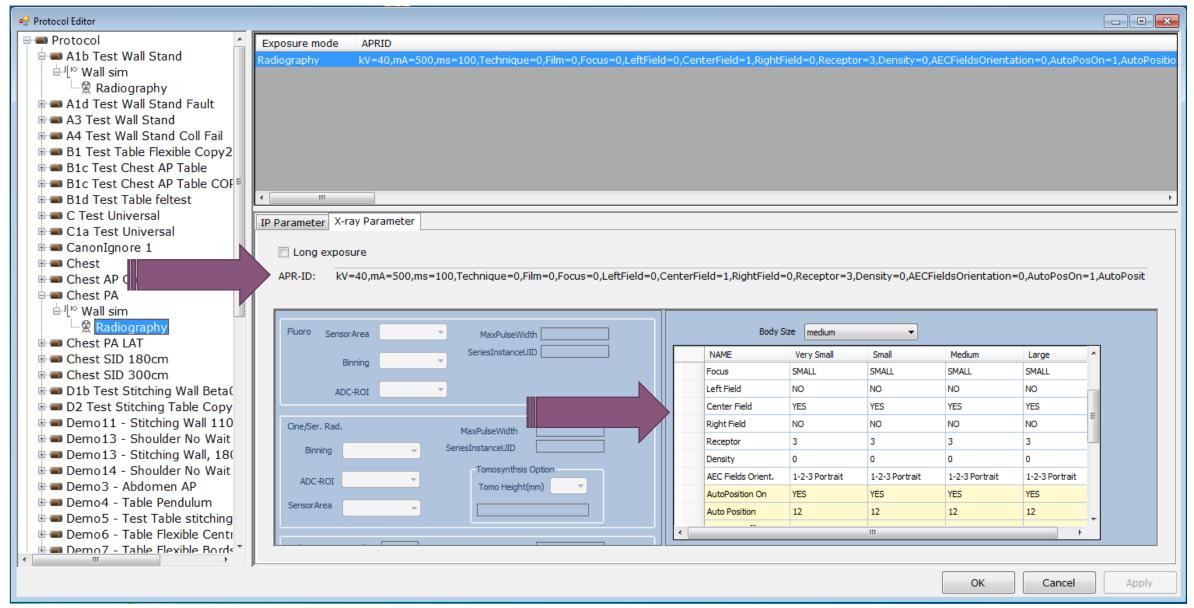












Which system do you work with? Aceso+ or Aceso?

PLEASE TYPE SYSTEM NAME IN CHAT



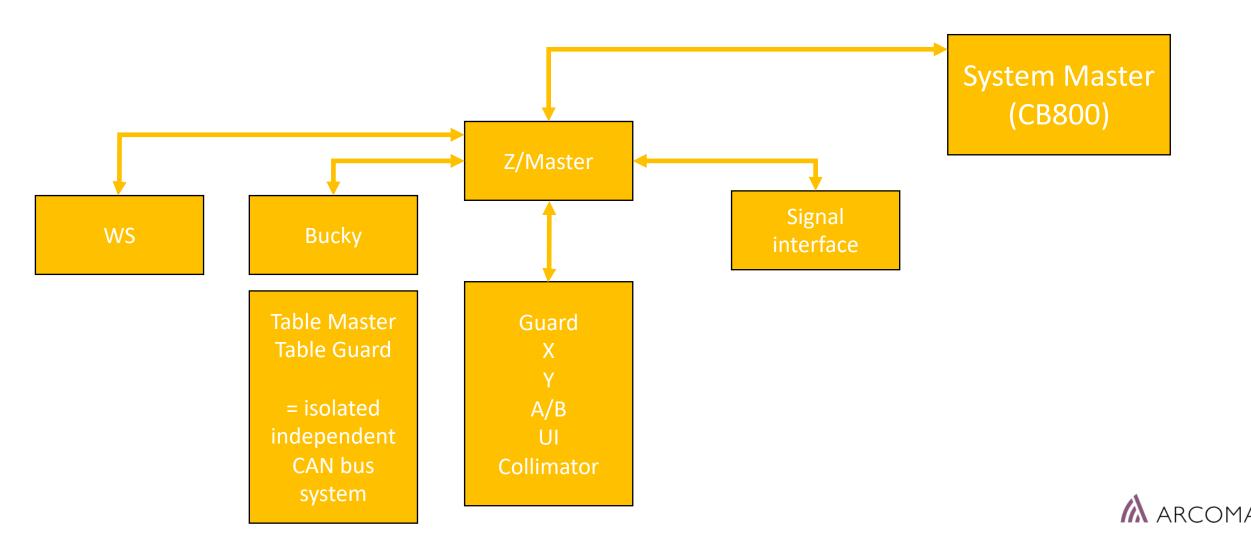
Aceso+ (Precision)



Aceso (Intuition)

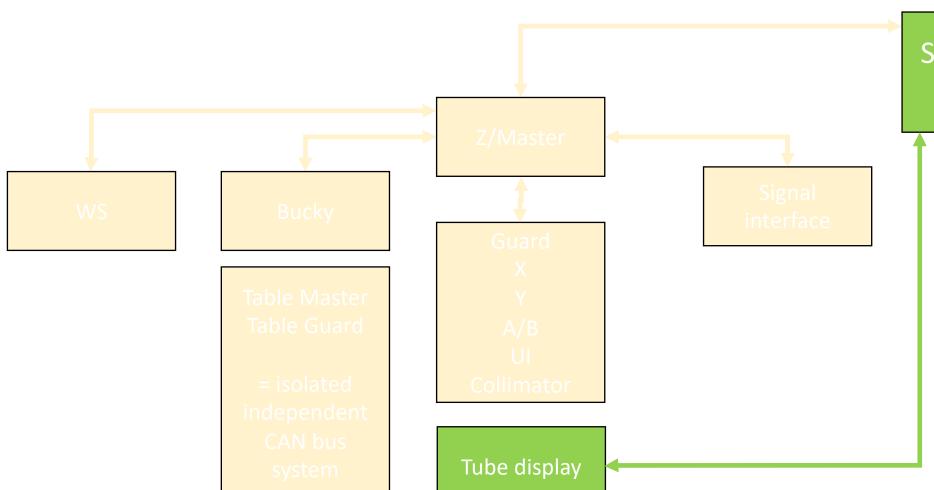


CAN BUS COMMUNICATION



ETHERNET COMMUNICATION

CPI Overwrap Software

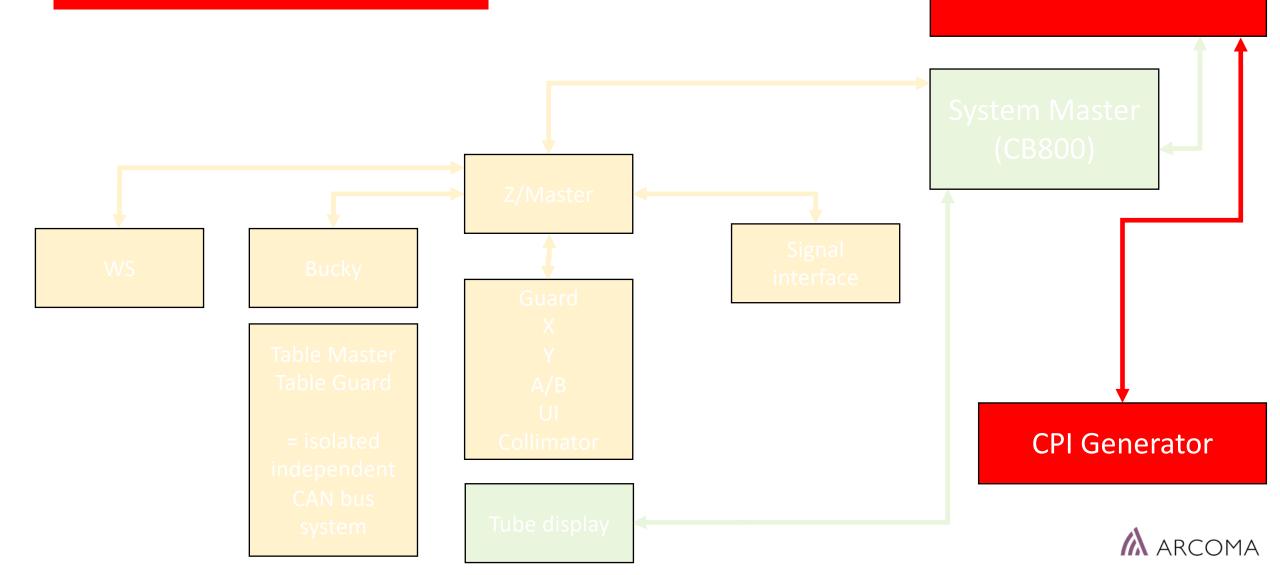


System Master (CB800)

M ARCOMA

SERIAL COMMUNICATION

CPI Overwrap Software



SERVICE TOOL CONNECTIONS Aceso+ **SERIAL COMMUNICATION** Service PC Z/Master **Programming** node **Table Master Table Guard** = isolated Collimator independent CAN bus system ARCOMA

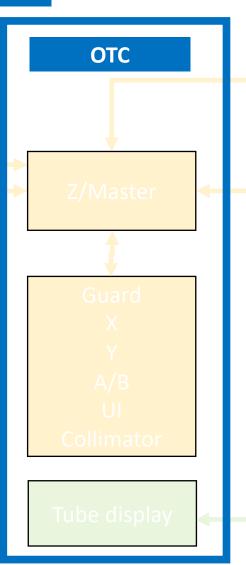
PHYSICAL LOCATIONS

WALL STAND

WS

TABLE

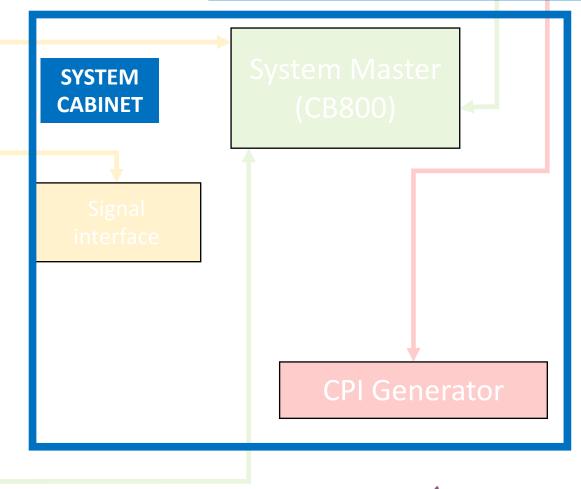
= isolated independent CAN bus system



CANON PC

CPI Overwrap Software

M ARCOMA



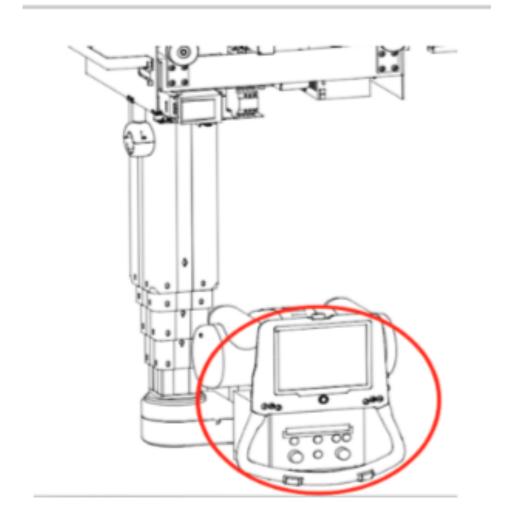
OVERVIEW OF SYSTEM COMPONENTS

CLARIFICATIONS

THE TUBE DISPLAY ASSEMBLY CONTAINS TWO COMMUNICATION MODULES:

- ETHERNET NODE COMMUNICATING WITH CB800

 CAN BUS NODE COMMUNICATING WITH COLLIMATOR AND Z/MASTER





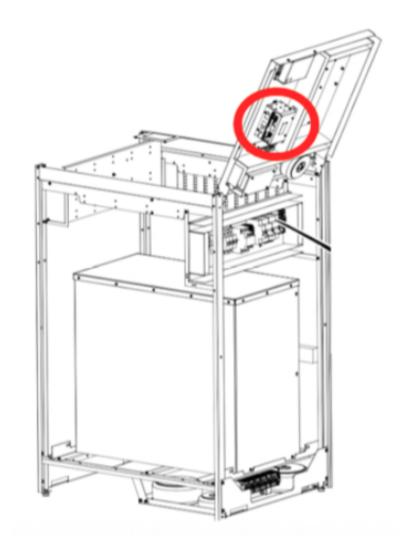
OVERVIEW OF SYSTEM COMPONENTS

CLARIFICATIONS

THE SYSTEM MASTER NODE (CB800)
COMMUNICATES BOTH BY ETHERNET AND CAN BUS:

- ETHERNET COMMUNICATION WITH TUBE DISPLAY AND CANON PC

- CAN BUS COMMUNICATION WITH Z/MASTER IN OTC

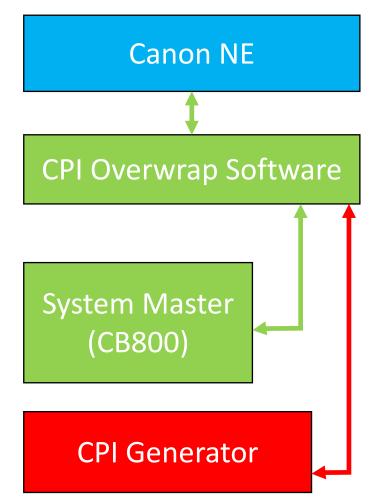




OVERVIEW OF SYSTEM COMPONENTS COMMUNICATION WITH CANON NE

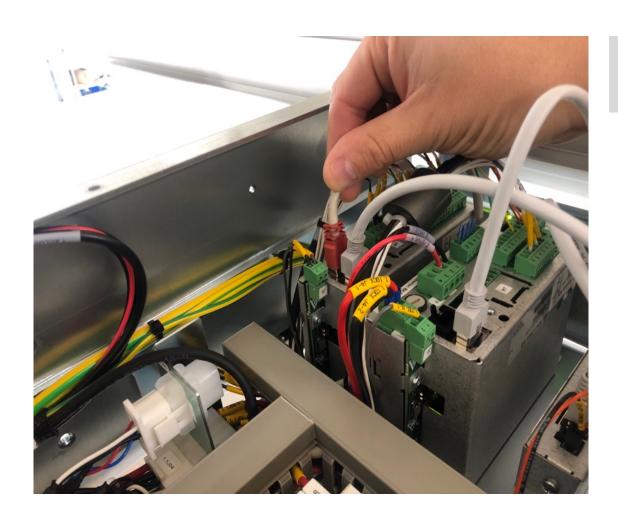
CPI AND CANON

- CPI Overwrap Software (and also Genware MP the generator service software) is stored on the Canon PC and communicates with CPI generator
- The CPI Overwrap Software communicates with CANON NE





SERVICE SOFTWARE CONNECTION Aceso+ Serial (RS 232)



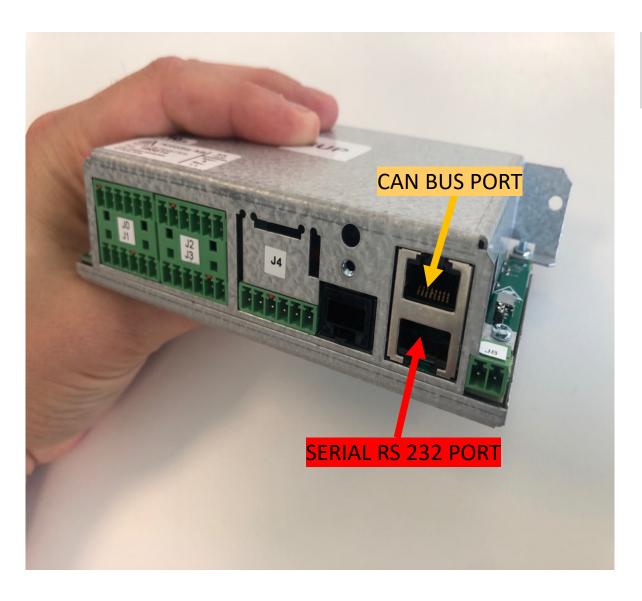
CONNECTING SERVICE SOFTWARE: RS 232 COMMUNICATION

When connecting the Arcoma Service Software we use the already wired RS 232 connection on the Z/Master node

CABLE ROUTED FROM Z/MASTER TO SYSTEM CABINET FOR EASIER CONNECTION



CAN bus / Serial RS 232 ports on CBDC-nodes



CONNECTING SERVICE SOFTWARE: RS 232 COMMUNCATION

We must always use RS 232 connection port for serial communication with any node

NOTE!

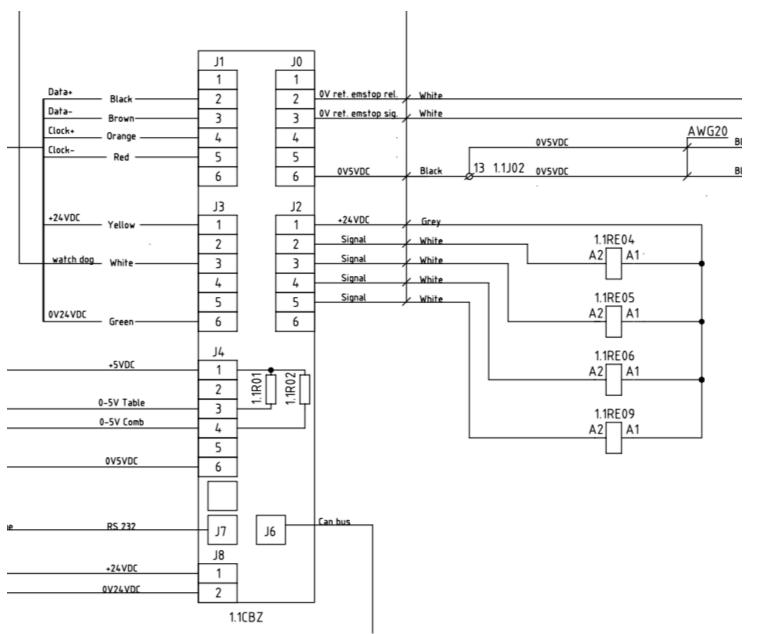
Connecting a serial cable to any CAN bus port will cause permanent damages to node



CAN bus nodes

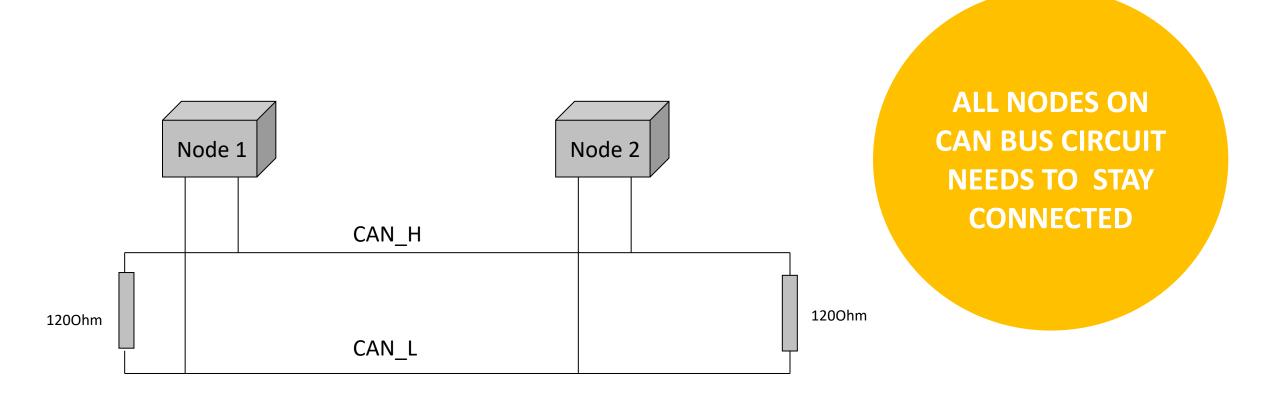
CONSISTENT ELECTRIC DESIGN:

- DIGITAL I/O = J0, J1, J2, J3
- ANALOGUE I/O = J4
- CAN BUS PORT = J6
- SERIAL PORT = J7
- 24 VDC POWER = J8





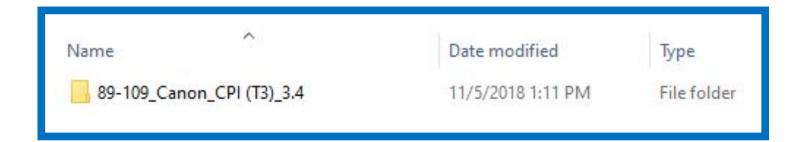
CAN BUS SYSTEMS IN GENERAL CLOSED CIRCUIT





SOFTWARE PACKAGES AND DOCUMENTATION

• All software packages have a bundle version number



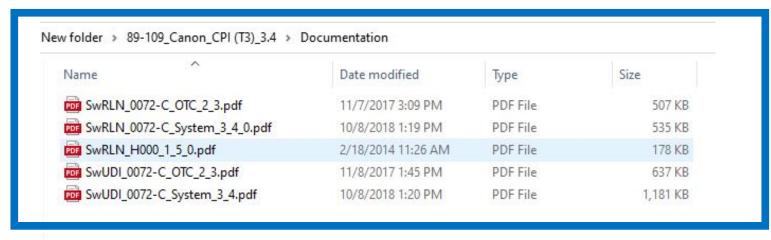




RLN AND UDI

All software packages always include two types of critical documents:

- The first one is called RLN
- The second one is called UDI.





UDI = UPDATE INSTRUCTION



RLN - Release notes

Release notes is used to determine which version of each node belonging to a specific software package.

One for OTC-level (CAN bus positioning system)



2.3 Update Instructions

See document SwUDI_0072-C_OTC_x_x.pdf

3 RELEASE NOTES

3.1 2.3

3.1.1 Software versions

Master/Z:	2.3.A
UI/Collimator:	1.4.A
Guard:	0.10.
SI:	2.0.A
X:	1.1.B
Y:	1.1.B
Alpha/Beta:	1.0.A
Bucky:	1.3.A
Wallstand:	1.3.A

SSW: 1.5.A

- 3.1.2 New functions
- 3.1.3 Enhancements and Bugfixes
 - Enhancements in stitching functionality. Overlap and collimator size can be adjusted.
- 3.1.4 Parameter changes



RLN – Release notes

And another one for system level (CB800, CPI overwrap)



2.1.2 Software compatibility

0072-C_OTC version 2.3

CANDevice version 1.5

CPI overwrap 3.4.0.0 & 3.6.0.0

- 2.2 Known Issues
- 2.3 Update Instructions

See document SwUDI_0072-C_System_x_x.pdf

- 3 RELEASE NOTES
- 3.1 3.4
- 3.1.1 Software versions

SystemMaster: 3.4.A

Display: 3.0.F

- 3.1.2 New functions
- 3.1.3 Enhancements and Bugfixes

The handling of preview images is improved.



UDI – Update Instruction

Same thing with the Update Instructions – there is one for OTC level and another one for system level.

- 6. Put on power to the board. The diodes on the board shall now follow the sequence:
 - Led 1 starts to blink.
 - Led 1 and 2 starts to blink when USB and file system is detected.
 - Led 1 and 3 starts to blink when the application is programmed.
 - Led 1 and 4 starts to blink when the programming of the board is finished.
- 7. When the programming is finished, remove the USB-memory stick.
 - The new application starts.

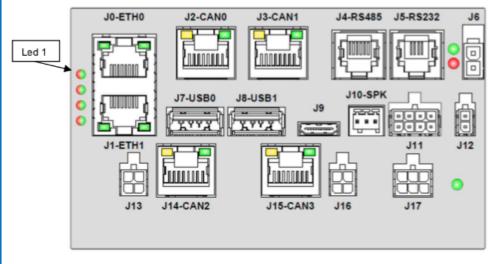


Figure: CB800 ports

4. Mark all possible setting and save, an example is snown in Figure 1:

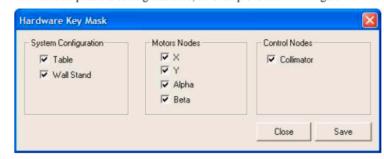


Figure 1: Hardware Key Mask

5. Restart the system.

4.1 Update Process

system:

To update the software

Connect the s
 Start the servi

3. Under "Edit"



SOFTWARE UPDATING DOCUMENTATION – HOW TO LOAD SW

HOW TO LOAD SOFTWARE

We have created a guidance document explaining the following:

- How to use the RLN and UDI documents
- In which order to read and determine versions.
- When and how to save a backup parameter (system config file)
- The difference between upgrading a complete system and replacing a single spare part containing software
- How to load software to both CAN bus and Ethernet nodes.

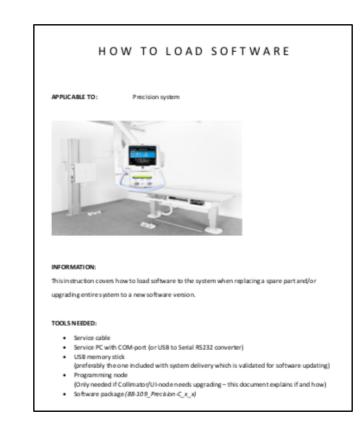




SOFTWARE UPDATING HOW TO LOAD SOFTWARE

Let's have a look at the document together:

How to load software



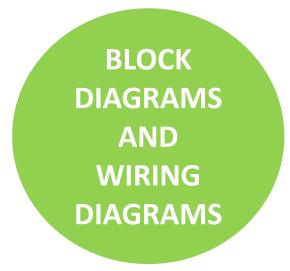




SCHEMATICS HOW TO NAVIGATE

There are 3 different types of schematics:

- SBD = System Block Diagram
- UBD = Unit Block Diagram
- WRD = Wiring Diagram

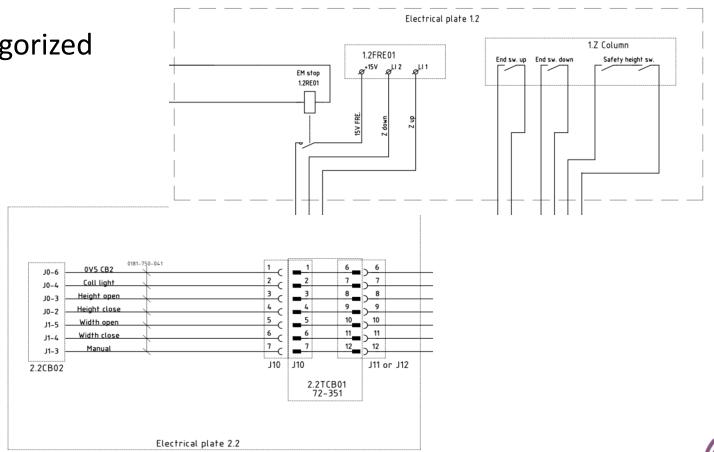




SCHEMATICS HOW TO NAVIGATE

All cables and wires are categorized with consistent names:

- 1.x = Tube stand
- 2.x = Table
- 3.x = Wallstand
- 4.x = System cabinet
- 5.x = Image system





SCHEMATICS HOW TO NAVIGATE EASILY

Different schematic types and consistent labeling

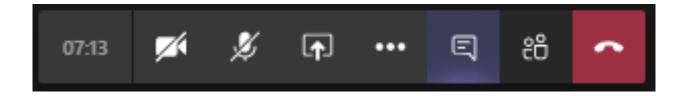
- Let's have a look at them!

Installation and Service manual





Questions?



Feel free to send us questions later:

erik.sall@arcoma.se or service@arcoma.se



THANK YOU

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